



The ideas developed at universities and research centres can end up as part of our every-day lives in the form of products, services and other innovations that make our lives easier. The *RecerCòmics* collection gives visibility to a selection of research centre spin-offs and knowledge transfer projects. A case in point, and the subject of this comic, is ABLE HUMAN MOTION S.L., which grew out of the Biomechanical Engineering Laboratory (BIOMEC), a Universitat Politècnica de Catalunya–BarcelonaTech (UPC) research group and one of the seven areas of the Research Centre for Biomedical Engineering (CREB). The comics also showcase the work of young illustrators. This time it featured the work of illustrator Laura Benedito Bernat, former student of Plastic Arts and Comic Design at the Escola d'Art Pau Gargallo.

http://universitatsirecerca.gencat.cat/recercomics

Xavier Roca (Barcelona, 1966). His first interest was in becoming a comic book artist, but, looking for job stability and showing incredible foresight, he decided to study journalism. He has written cultural pieces and film reviews for the newspapers Avui and El Punt Avui and writes for Catorze, El Temps de les Arts and Gran enciclopèdia catalana. As a comic book and graphic humour scriptwriter he has had work published in El Jueves, Avui, El Periódico and La Vanguardia and currently writes and draws a monthly strip for the magazine El Castell.

Laura Benedito Bernat (Barcelona, 1998). Drawing and design have always been one of the most important parts of her life. She wholeheartedly believes her training began with her father (a graphic designer), when he taught her how to draw a water jug when she was eight. After that she spent all her free time, summer and holidays pencil in hand, making up characters for whom she imagined worlds she could not yet draw. With the support and trust of her parents, she studied Fine Arts at the University of Barcelona and, following a pandemic and a rediscovery of her interest in comics, went

on to study Comic Design at Escola d'Art Pau Gargallo. Today she combines a boring part-time job with one that is much more stimulating: that of a commissioned illustrator. In the future she sees herself working as a character designer and illustrator for a studio, surrounded by fantastic worlds.

Script: Xavier Roca.

Illustrations and cover: Laura Benedito Bernat.

In conjunction with: Toni Benages, teacher of Plastic Arts and Comic Design at the Escola d'Art Pau Gargallo; Ivan Camps Rivas (first person with a spinal cord injury to test pilot the ABLE exoskeleton); Alfons Carnicero Carmona (cofounder and CEO of ABLE Human Motion); Alex Garcia Farreny (co-founder and technical director of ABLE Human Motion); Josep Maria Font Llagunes (co-founder of ABLE Human Motion, full professor of Mechanical Engineering and director of the UPC BIOMEC research group) and Maria Shulaeva (marketing expert at ABLE Human Motion).

Editorial board: Joan Gómez Pallarès, Olga Alay, Salvador Maturana, Olga Campillo, Oriol Homar.

Translation and correction: Tys 96, SL.

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© Laura Benedito, illustrations.

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RecerCòmics no. 7



STORY: XAVIER ROCA

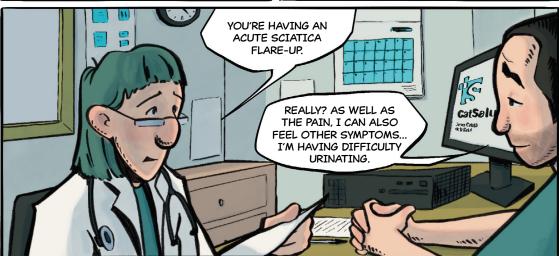
ART: LAURA BENEDITO





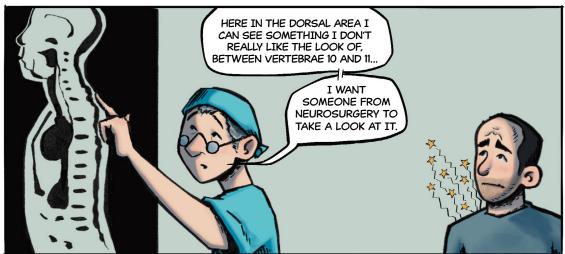


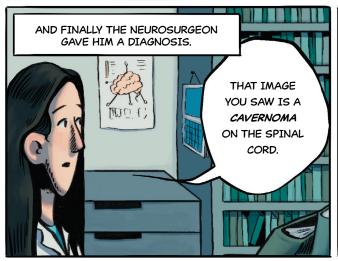




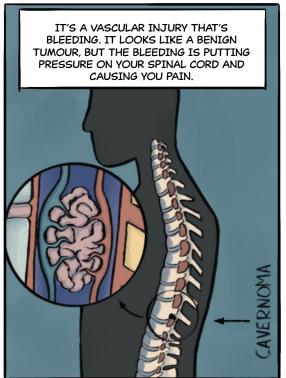








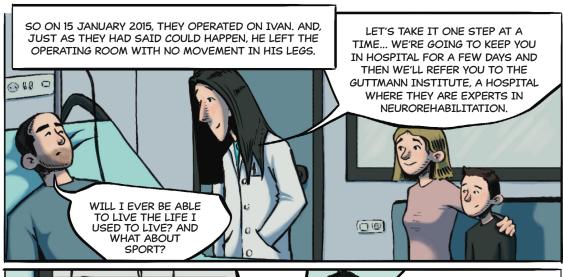


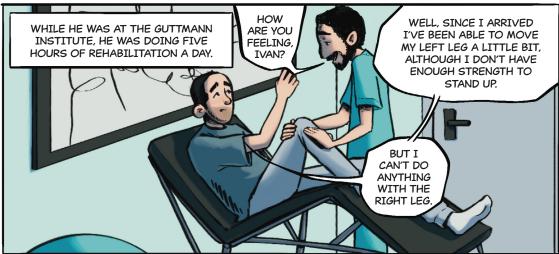


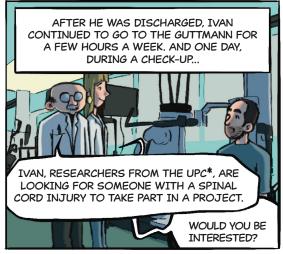










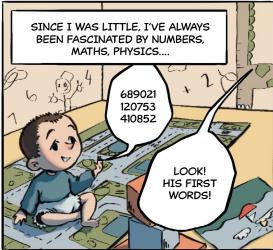




^{*}UPC: UNIVERSITAT POLITÈCNICA DE CATALUNYA-BARCELONATECH.

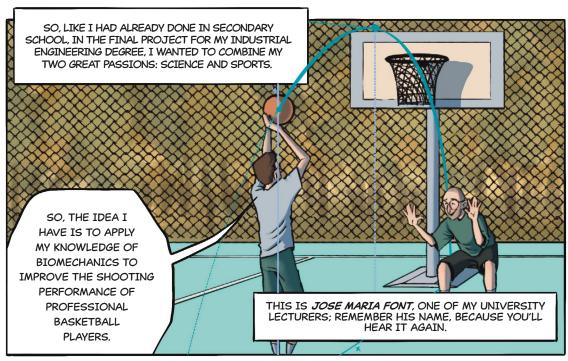








ONE OF THE FIRST THINGS I'VE FOUND IN COMMON WITH OUR FRIEND IVAN IS THAT I'VE ALWAYS BEEN VERY KEEN ON SPORTS.







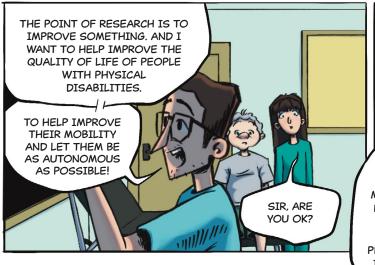






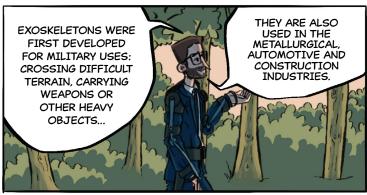






SO I DID THE BIOMEDICAL
SPECIALISATION ON THE UPC'S
MASTER'S DEGREE IN INDUSTRIAL
ENGINEERING. I SPENT A PERIOD
AT THE GUTTMANN INSTITUTE,
I TALKED TO DOCTORS,
PHYSIOTHERAPISTS AND PATIENTS,
I DESIGNED KNEE IMPLANTS IN A
COMPANY IN HAMBURG...

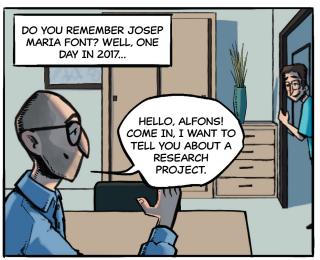




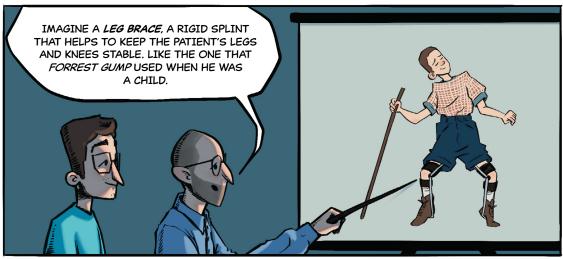


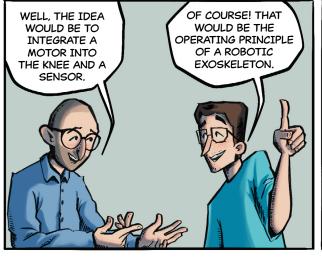




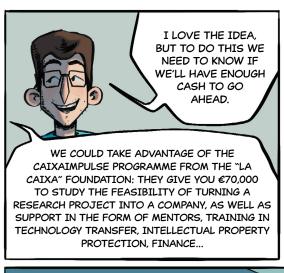




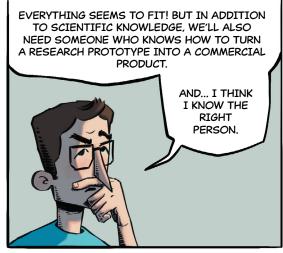






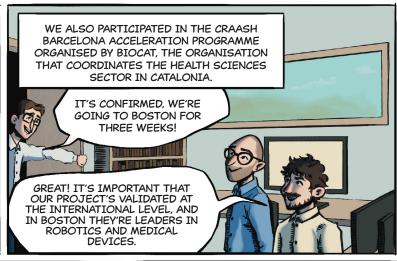


IT WAS ALEX GARCIA, A FORMER UNIVERSITY FRIEND OF MINE WHO WAS WORKING AT AN







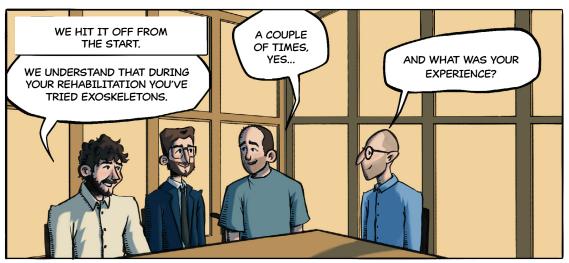






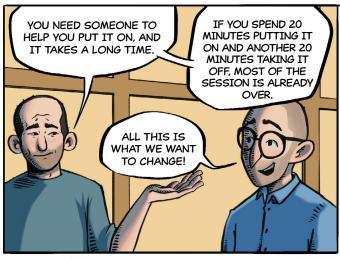






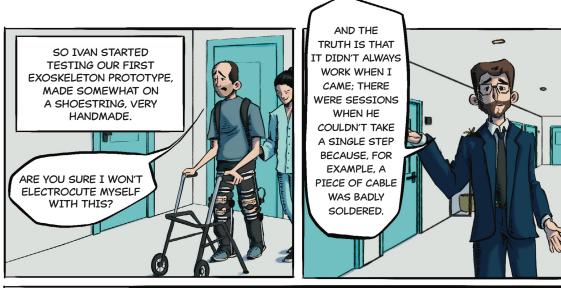


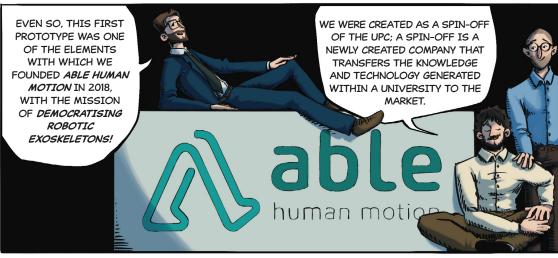






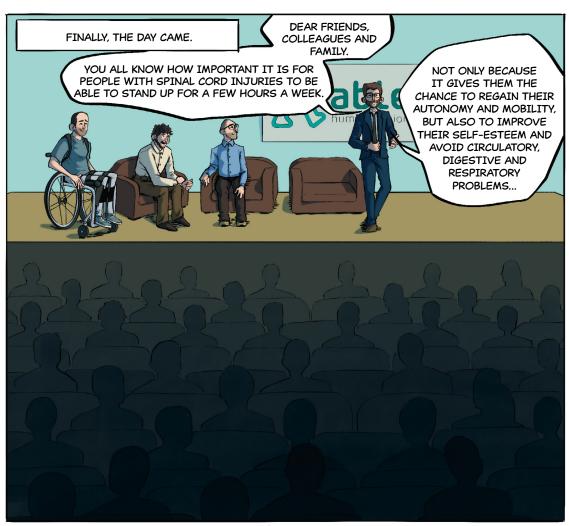




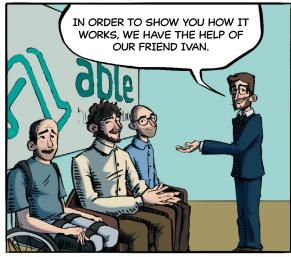












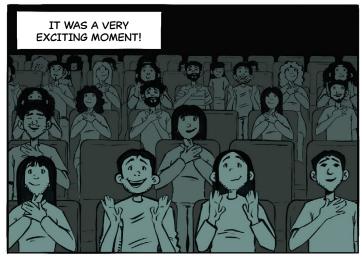




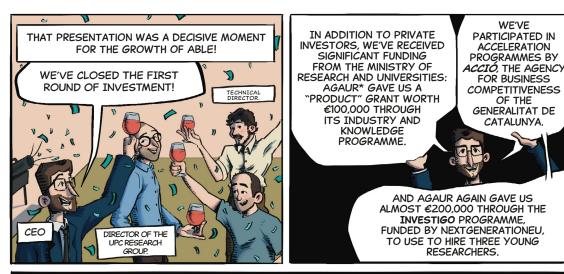


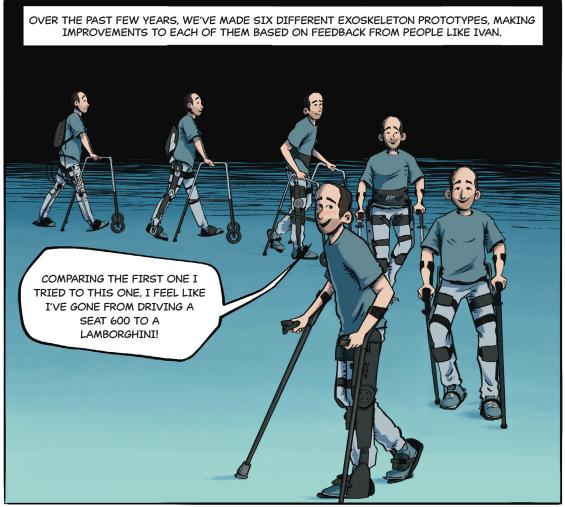












*AGAUR: AGENCY FOR MANAGEMENT OF UNIVERSITY AND RESEARCH GRANTS.

OUR EXOSKELETON IS LIKE ROBOTIC TROUSERS WITH INERTIAL SENSORS

- LIKE THE ONES IN A MOBILE PHONE - WHICH DETECT THE POSITION AND ACCELERATION OF THE LEGS. BASED ON THIS INFORMATION, ALGORITHMS DECIDE WHEN AND HOW THE USER WANTS TO TAKE EACH STEP.

IN THE HIP AND KNEE JOINTS, FOUR *MOTORS*PERFORM THE FUNCTIONS OF THE MUSCLES,
TRYING TO ACHIEVE THE MOST NATURAL
MOVEMENT POSSIBLE.







